

# Phalanx: An Flexible and Extensible Assembly/Field Evaluation Kernel For Handling Complexity in Simulation

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# Acknowledgements

- Phalanx Contributors
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  - Pavel Bochev
  - Dennis Ridzal
  - Andy Salinger



# Motivation

- Assembly for general FE/FV PDE discretizations gets quite complex when supporting arbitrary equation sets.
- Issues to Address:
  - Compact and uniform user interface for extensibility
  - Flexibility to easily swap equation sets, material models and material properties while maintaining efficiency
  - Support for user defined data types
  - Support for embedded technology
  - Good OO-design/Code reuse
- Generalization and unification of:
  - Expression Manager in SIERRA/Aria
  - Variable Manager in Charon



# Overview

- Phalanx is a local field evaluation kernel designed for assembly of arbitrary equation sets (i.e. evaluating residuals and Jacobians).
  - Equation sets, material models might change drastically
- Decompose a complex problem into a number of simpler problems with managed dependencies
  - Supports rapid development and extensibility
  - Consistent evaluation of fields as dependencies change
- Phalanx supports arbitrary user defined **data types** and **evaluation types** through template metaprogramming.
  - Flexibility for direct integration with user applications
  - Provides extensive support for embedded technology such as automatic differentiation for sensitivities and uncertainty quantification.
- Efficient evaluation of fields using worksets and memory management for efficient use of cache.

# Complex Dependency Chains

Momentum  $\frac{\partial(\rho\mathbf{v})}{\partial t} + \nabla \cdot (\rho\mathbf{v} \otimes \mathbf{v} + \mathbf{T}) - \rho\mathbf{g} = 0$

Continuity  $\frac{\partial\rho}{\partial t} + \nabla \cdot (\rho\mathbf{v}) = 0$

Energy  $\rho C_p \frac{\partial T}{\partial t} + \nabla \cdot (\rho C_p T \mathbf{v} - \mathbf{q}) + s = 0$

Species  $\rho \frac{\partial y_i}{\partial t} + \nabla \cdot (\rho \mathbf{v} y_i + \mathbf{j}_k) + W_i \dot{\omega}_i \quad i = 1 \dots N_{sp}$

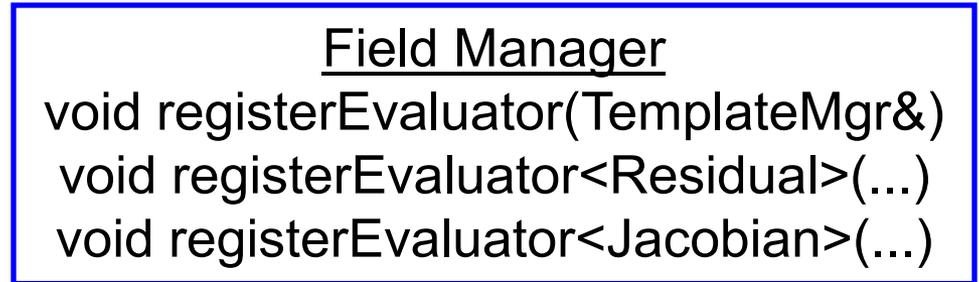
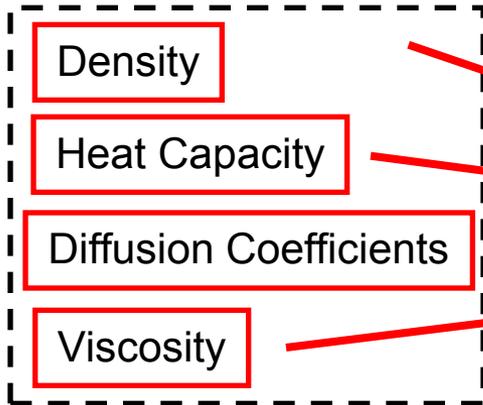
$$\mathbf{T} = P\mathbf{I} + \frac{2}{3}\mu(\nabla \cdot \mathbf{u})\mathbf{I} - \mu(\nabla\mathbf{u} + \nabla\mathbf{u}^T) \quad \mathbf{q} = -k\nabla T$$

$$\mathbf{j}_k = \rho y_k \frac{1}{x_k \bar{W}} \sum_{j=1}^K W_j D_{kj} \nabla x_j$$

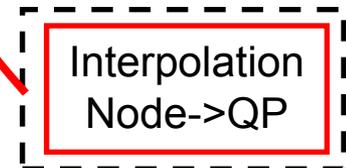
- Complexity spirals when we add new equations, operators, use subsets, etc...
  - Swap eqns/models at runtime (no complex if/switch statements)
- **Automatically adjust the dependency tree**  $\rho(T, P) \longrightarrow \rho(y_i, P, T)$
- Separate fields so that they are evaluated only once (density)

# Idea: Evaluators (Expressions)

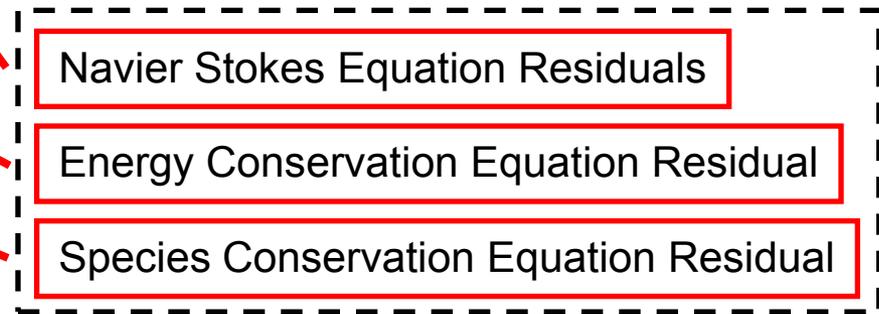
## Material Property Library



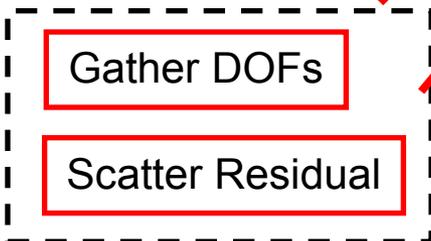
## FEM



## Physics/Equation Set



## Solver



Evaluators can be registered anytime before postRegistrationSetup()

# Evaluator Anatomy

$$\rho \frac{\partial y_i}{\partial t} + \nabla \cdot (\rho \mathbf{v} y_i) + \nabla \cdot \mathbf{j}_k + W_i \dot{\omega}_i \Rightarrow F_n = \int_{\Omega} \nabla \phi_n \cdot \mathbf{j}_k d\Omega$$

$$F_n = \int_{\Omega} \nabla \phi_n \cdot \mathbf{j}_k d\Omega$$

@ node points

- Evaluates one or more fields

$$\mathbf{j}_k = \rho y_k \frac{1}{x_k \bar{W}} \sum_{j=1}^K W_j D_{kj} \nabla x_j$$

@ integration points

- Depends on one or more fields

$\rho$

@ integration points

- **CTOR**: Size the fields
- **Setup Method**: Get pointers to memory

$D_{il}$

$\nabla x_i$

@ integration points

- **Evaluate Method**: Evaluate the field(s)

$x_i$

@ integration points

- Intrepid package does the final integration

$T$

$P$

$y_i$

$W_i$

@ basis points

$T$

$P$

$y_i$

$x_i$

$W_i$





# Idea: Chain of Evaluators

- Phalanx FieldManager will
  - Determine which evaluators to call
  - The order to call the evaluators for consistency
  - Perform the evaluation on a workset

```
field_manager.evaluateFields<Residual>(workset);
```

```
field_manager.evaluateFields<Jacobian>(workset);
```

# Evaluators: Simple for Users

- We must simplify interfaces for analysts to implement
  - Don't expose entire equation set to users
  - Hide advanced c++ (i.e. templating) from analysts looking to add new equations and material models
  - Don't have to know about derivatives/solver techniques

$$\mathbf{q} = -\rho k \nabla T$$

```
PHX_EVALUATOR_CLASS(EnergyFlux)

Field< MyVector<ScalarT> > flux;

Field< ScalarT > density;
Field< ScalarT > k;
Field< MyVector<ScalarT> > grad_temp;

int points_per_cell;

PHX_EVALUATOR_CLASS_END
```

```
PHX_EVALUATE_FIELDS(EnergyFlux,workset)
{
  int size = workset.num_cells * points_per_cell;

  for (int i = 0; i < size; ++i)
    flux[i] = -density[i] * k[i] * grad_temp[i];
}
```

Skipped CTOR (field sizing),  
Setup (get pointers to memory)



# Workset/Memory Management

- Break work up into worksets
  - Chunk of cells in finite element/volume calculation
- Memory allocation of all fields of all scalar types for an evaluation type is done in a single contiguous array!
  - Possibly fit all fields in cache
  - User defined allocators (template parameter in Traits)
- Leverage BLAS in evaluators



## What does this buy you?

- Consistent Evaluations: Dependencies are ensured to be up-to-date
- Evaluate each field once per cell
  - No recalculation of temporaries
- **Flexible and Extensible**: each simpler piece becomes an extension point that can be swapped out with different implementations
- Easier to craft code because each piece is simpler, more focused and **easier to test** in isolation
- **Minimal interface**: isolate users from bulk of assembly process
- Efficient: use of worksets
  - Block evaluations → Blas
  - Possibly fits into cache

# Embedded Technology!!!

Field Manager is templated on Evaluation Type

## Concept: Evaluation Types

• Residual  $F(x, p)$

• Jacobian  $J = \frac{\partial F}{\partial x}$

• Tangent  $\frac{\partial F}{\partial p}$

• Stochastic Galerkin Residual

• Stochastic Galerkin Jacobian

## Scalar Types

`double`

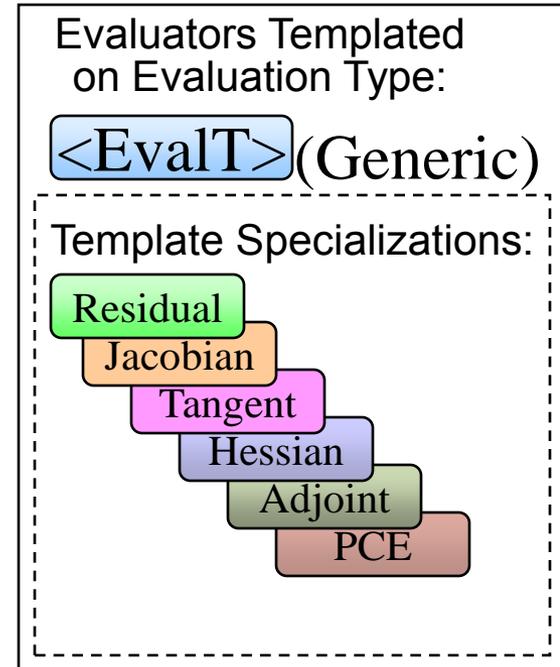
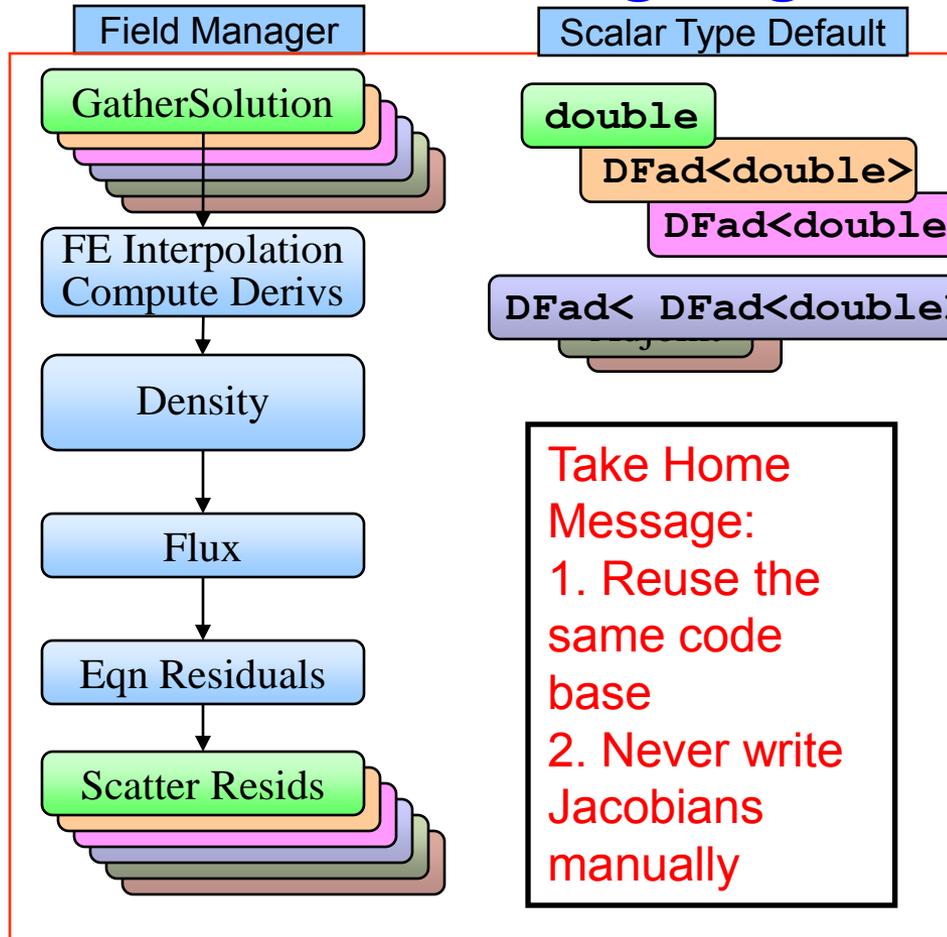
`Sacado::FAD::DFad<double>`

`Sacado::FAD::DFad<double>`

`Sacado::PCE::OrthogPoly<double>`

`Sacado::Fad::DFad< Sacado::PCE::OrthogPoly<double> >`

# Transformational PDE Assembly using Agile Components



**Packages / Libraries:**

- Sacado: Automatic Differentiation
- Phalanx: Field Manager, Evaluators
- Intrepid: Compatible Discretizations
- iTAPS: Mesh interface

**Rapid, Transformational, Scalable**

# Example Traits

```
struct MyTraits : public PHX::TraitsBase {
```

```
    typedef double RealType;  
    typedef Sacado::Fad::DFad<double> FadType;
```

← Declare Scalar Types

```
    struct Residual { typedef RealType ScalarT; };  
    struct Jacobian { typedef FadType ScalarT; };
```

← Declare Evaluation Types

```
    typedef boost::mpl::vector<Residual, Jacobian> EvalTypes;
```

← Evaluation Types

```
    // Residual (default scalar type is RealType)  
    typedef boost::mpl::vector< RealType,  
                               MyVector<RealType>,  
                               MyMatrix<RealType>  
    > ResidualDataTypes;
```

← Declare Residual  
Data Types

```
    // Jacobian (default scalar type is Fad<double>)  
    typedef boost::mpl::vector< FadType,  
                               MyVector<FadType>,  
                               MyMatrix<FadType>  
    > JacobianDataTypes;
```

← Declare Jacobian  
Data Types

```
    // Maps the key EvalType a vector of DataTypes  
    typedef boost::mpl::map<  
        boost::mpl::pair<Residual, ResidualDataTypes>,  
        boost::mpl::pair<Jacobian, JacobianDataTypes>  
    >::type EvalToDataMap;
```

← Maps Evaluation Types  
to Data Types

# Multidimensional Arrays

(Shards – C. Edwards next)

```
PHX_EVALUATOR_CLASS(EnergyFlux)
```

```
Field< MyVector<ScalarT> > flux;
```

```
Field< ScalarT > density;
```

```
Field< ScalarT > k;
```

```
Field< MyVector<ScalarT> > grad_temp;
```

```
int points_per_cell;
```

```
PHX_EVALUATOR_CLASS_END
```

```
PHX_EVALUATE_FIELDS(EnergyFlux,workset)
```

```
{
```

```
int size = workset.num_cells * points_per_cell;
```

```
for (int i = 0; i < size; ++i)
```

```
flux[i] = -density[i] * k[i] * grad_temp[i];
```

```
}
```

```
PHX_EVALUATOR_CLASS(EnergyFlux)
```

```
MDField<ScalarT,Cell,QuadPoint,Dim> flux;
```

```
MDField<ScalarT,Cell,QuadPoint> density;
```

```
MDField<ScalarT,Cell,QuadPoint> dc;
```

```
MDField<ScalarT,Cell,QuadPoint,Dim> grad_temp;
```

```
int num_qp;
```

```
int num_dim;
```

```
PHX_EVALUATOR_CLASS_END
```

```
PHX_EVALUATE_FIELDS(EnergyFlux,workset)
```

```
{
```

```
int num_cells = workset.num_cells;
```

```
for (int cell = 0; cell < num_cells; ++cell)
```

```
for (int qp = 0; qp < num_qp; ++qp)
```

```
for (int dim = 0; dim < num_dim; ++dim)
```

```
flux(cell,qp,dim) =
```

```
- density(cell,qp) * dc(cell,qp) * grad_temp(cell,qp,dim);
```

```
}
```

Optional compile time checked  
access



## In closing...

- This package is very advanced
  - C++ templates and template metaprogramming
  - One developer will need to know templates to set up
  - Everyone else only needs to write evaluators (very minimal template code)
- Think hard before using
  - This is a hammer, its not right for every PDE code, especially if your equation set/models doesn't change
- “My understanding keeps changing...” – Andy Salinger
- Don't hesitate to ask for help!
- <http://trilinos.sandia.gov/packages/phalanx>: a very detailed users guide.



# Phalanx Summary

- Assembly kernel for cell based discretization of PDEs
- Breaks complex problems into simpler pieces
  - Automatically manage complex dependency chains
  - Easier to unit test
  - Don't expose fully complex system to the user – only expose exactly what they need to write a user defined function
- Supports rapid development and extensibility
  - Easily swap evaluation routines
  - Easily swap dependency trees
- Arbitrary user defined data types and evaluation types: C++  
Template metaprogramming
- Embedded technology support