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Teuchos::RCP Beginner's Guide

An Introduction to the Trilinos Smart Reference-Counted Pointer Class for (Almost) Automatic Dynamic Memory Management in C++

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Abstract

Dynamic memory management in C++ is one of the most common areas of difficulty and errors for amateur and expert C++ developers alike. The improper use of `operator new` and `operator delete` is arguably the most common cause of incorrect program behavior and segmentation faults in C++ programs. Here we introduce a templated concrete C++ class `Teuchos::RCP`, which is part of the Trilinos tools package `Teuchos`, that combines the concepts of smart pointers and reference counting to build a low-overhead but effective tool for simplifying dynamic memory management in C++. We discuss why the use of raw pointers for memory management, managed through explicit calls to `operator new` and `operator delete`, is so difficult to accomplish without making mistakes and how programs that use raw pointers for memory management can easily be modified to use `RCP`. In addition, explicit calls to `operator delete` is fragile and results in memory leaks in the presence of C++ exceptions. In its most basic usage, `RCP` automatically determines when `operator delete` should be called to free an object allocated with `operator new` and is not fragile in the presence of exceptions. The class also supports more sophisticated use cases as well. This document describes just the most basic usage of `RCP` to allow developers to get started using it right away. However, more detailed information on the design and advanced features of `RCP` is provided by the companion document “`Teuchos::RCP : The Trilinos Smart Reference-Counted Pointer Class for (Almost) Automatic Dynamic Memory Management in C++`”.

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The format of this report is based on information found in [4].

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Teuchos::RCP Beginner's Guide

An Introduction to the Trilinos Smart Reference-Counted Pointer Class for (Almost) Automatic Dynamic Memory Management in C++

1 Introduction

The main purpose of this document is to provide a quick-start guide on how to incorporate the reference-counting smart pointer class `Teuchos::RCP` into C++ programs that use dynamic memory allocation and object orientation. This code is included in the Trilinos [3] tools package `Teuchos`. The design of `Teuchos::RCP` is based partly on the interface for `std::auto_ptr<>` and Items 28 and 29 in "More Effective C++" [5]. In short, RCP allows one client to dynamically create an object (using operator `new` for instance), pass the object around to other clients that need to access the object and never require any client to explicitly call operator `delete`. The object will (almost magically) be deleted when all of the clients remove their references to the object. In principle, this is very similar to the type of garbage collection that is in languages like Perl and Java. There are some pathological cases (such as the classic problem of circular references, see [5, Item 29, page 212]) where RCP will result in a memory leak, but these situations can be avoided through the careful use of RCP. However, realizing the potential of hands-off garbage collection with RCP requires following some rules. These rules are partially spelled out in the form of commandments in Appendix C.

Note that direct calls to operator `delete` are discouraged in modern C++ programs that are designed to be robust in the presence of C++ exception handling. This is because the raw use of operator `delete` often results in memory leaks when exceptions are thrown. For example, in the code fragment:

```
void someFunction() {
    A *a = new A;
    a->f();
    delete a;
}
```

if an exception is thrown in the function call `a->f()` then the statement `delete a` will never be

executed and a memory leak will have been created. The class `std::auto_ptr<>` was added to the standard C++ library (see [5, Items 9 and 10]) to protect against these types of memory leaks. For example, the rewritten function:

```
void someFunction() {
    std::auto_ptr<A> a(new A);
    a->f();
}
```

is robust in the event of exceptions and no memory leak will occur. However, `std::auto_ptr<>` can not be used to share a resource between two or more clients and therefore is not an answer to the issue of general garbage collection. The class `RCP` not only is robust in the event of exceptions but also implements reference counting and is therefore more general (but admittedly more complex and expensive) than `std::auto_ptr<>`.

The use of `RCP` is critically important in the development and maintenance of large complex object-oriented programs composed of many separately-developed pieces (such as Trilinos). This discussion assumes that the reader has a basic familiarity and some programming experience with C++ and has at least been exposed to the basic concepts of object-oriented programming (good sources include [2] and [6]). Furthermore, the reader should be comfortable with the use of C++ pointers and references.

The appendices contain basic reference material for `RCP`. In many respects, the appendices are the most important contribution of this document. For those readers that like to see the C++ declarations right away, Appendix A contains the C++ declarations for the template class `RCP` and some important associated non-member templated functions. Appendix B is a short reference-card-like quick-start for the use of `RCP`. The quick-start in this appendix shows how to create `RCP` objects from raw C++ pointers, how to represent different forms on constantness, cast from one pointer type to another, access the underlying reference-counted object as well as to associate and manage extra data. Appendix C gives some commandments for the use of `RCP` and reinforces the material in Appendix B. Appendix D gives tables of recommended idioms for how to pass raw C++ objects and `RCP`-wrapped objects to and from functions. Appendix E gives a listing for an example program that uses raw pointer variables and direct calls to `operator new` and `operator delete` while Appendix F shows a refactoring of this example program to use `RCP`.

Note! Anxious readers are encouraged to jump directly to Appendix E and F to get an idea of what `RCP` is all about. This example, together with the reference material in the appendices, should be enough for semi-experienced C++ developers to start using `RCP` right away.

For less anxious readers, in the following section, we describe why the use of raw C++ pointers and raw calls to `operator new` and especially `operator delete` is difficult to program correctly in even moderately complex C++ programs. We then discuss the different ways C++ pointers are used in such programs and describe how to refactor these programs to replace some of the raw C++ pointers and raw calls to `operator delete` with `RCP`. In the following discussion we will define

persisting and *non-persisting* associations and will make a distinction between them (see page 11). RCP is recommended for use only with *persisting* associations. The consistent use of RCP extends the vocabulary of C++ in helping to distinguish between these two types of relationships. In addition, RCP is designed for the memory management of individual objects, not raw C++ arrays of objects. Array allocation and deallocation should be performed using standard C++ containers such as `std::vector<>`, `std::valarray<>` or some other such convenient C++ array class but the best choice is typically a debug range-checked class like `Teuchos::Array`. However, it is quite common to dynamically allocate arrays of RCP objects and use RCP to manage the lifetime of such array class objects.

2 An example C++ program

The use of object-oriented (OO) programming in C++ is the major motivation for the development of RCP. OO programs are characterized by the use of abstract classes (i.e. interfaces) and concrete subclasses (i.e. implementations). In OO programs it is common that the selection of which concrete subclass(es) to use is not known until runtime. The “Abstract Factory” [2] is a popular design pattern that allows the flexible runtime selection of what concrete subclasses to create.

Below we describe a fictitious program that demonstrates some of the typical features of an OO program that uses dynamic memory management in C++. In this simple program, handling memory management using raw C++ pointers and calls to operator `new` and operator `delete` will appear fairly easy but larger more realistic OO programs are much more complicated and it is definitely not easy to do memory management without some help.

2.1 Example C++ program using raw dynamic memory management

One of the predominate features of this example program is the use of the following abstract interface base class `UtilityBase` that defines an interface to provide some useful capability.

```
class UtilityBase {
public:
    virtual void f() const = 0;
};
```

In our example program, `UtilityBase` will have two subclasses where one or the other will be used at runtime.

```
class UtilityA : public UtilityBase {
public:
```

```

    void f() const { std::cout<<"\nUtilityA::f() called, this="<<this<<"\n"; }
};

class UtilityB : public UtilityBase {
public:
    void f() const { std::cout<<"\nUtilityB::f() called, this="<<this<<"\n"; }
};

```

In this example program the above implementation functions just print to standard out.

Some of the clients in this program have to create `UtilityBase` objects without knowing exactly what concrete subclasses are being used. This is accomplished through the use of the “Abstract Factory” design pattern [2]. For `UtilityBase`, the abstract factory looks like

```

class UtilityBaseFactory {
public:
    virtual UtilityBase* createUtility() const = 0;
};

```

and has the following factory subclasses for creating `UtilityA` and `UtilityB` objects.

```

class UtilityAFactory : public UtilityBaseFactory {
public:
    UtilityBase* createUtility() const { return new UtilityA(); }
};

class UtilityBFactory : public UtilityBaseFactory {
public:
    UtilityBase* createUtility() const { return new UtilityB(); }
};

```

Now let’s assume that our example program has the following client classes.

```

// Simple client with no state
class ClientA {
public:
    void f( const UtilityBase &utility ) const { utility.f(); }
};

// Client that maintains a pointer to a Utility object
class ClientB {
    UtilityBase *utility_;
public:

```

```

ClientB() : utility_(0) {}
~ClientB() { delete utility_; }
void initialize( UtilityBase *utility ) { utility_ = utility; }
void g( const ClientA &a ) { a.f(*utility_); }
};

// Client that maintains pointers to UtilityFactory and Utility objects
class ClientC {
    const UtilityBaseFactory *utilityFactory_;
    UtilityBase *utility_;
    bool shareUtility_;
public:
    ClientC( const UtilityBaseFactory *utilityFactory, bool shareUtility )
        :utilityFactory_(utilityFactory),
        utility_(utilityFactory->createUtility())
        ,shareUtility_(shareUtility) {}
    ~ClientC() { delete utilityFactory_; delete utility_; }
    void h( ClientB *b ) {
        if( shareUtility_ ) b->initialize(utility_);
        else b->initialize(utilityFactory_->createUtility());
    }
};

```

The type of logic used in `ClientC` for determining when new objects should be created or when objects should be reused and passed around is common in larger more complicated OO programs.

The above client classes demonstrate two different types of associations between objects: *non-persisting* and *persisting*.

Non-Persisting associations exist only within a single function call and do not extend after the function has finished executing. For example, objects of type `ClientA` and `UtilityBase` have a non-persisting relationship through the function `ClientA::f(const UtilityBase &utility)`. Likewise, objects of type `ClientB` and `ClientA` have a non-persisting association through the function `ClientB::g(const ClientA &a)`.

Persisting associations are where a relationship between two objects exists past a single function call. The most typical kind of persisting association in an OO C++ program is where one object maintains a private pointer data member to another object. For example, persisting associations exist between a `ClientC` object, a `UtilityBaseFactory` and a `UtilityBase` object through the the private C++ pointer data members `ClientC::utilityFactory_` and `ClientC::utility_` respectively. Likewise, a persisting association exists between a `ClientB` object and a `UtilityBase` object through the private pointer data member `ClientB::utility_`.

Persisting relationships are significantly more complex than non-persisting relationships since a persisting relationship usually implies that some objects must be responsible for the lifetime of other objects. This is never the case in a non-persisting relationship as defined above.

Appendix E shows an example program that uses all of the C++ classes described above. The program in Appendix E has several memory management problems. An astute reader will notice that the `UtilityBaseFactory` created in `main()` gets deleted twice; once in the destructor for the `ClientC` object `c` and again at the end of `main()` in an explicit call to `operator delete`. This problem could be fixed in this program by arbitrating “ownership” of the `UtilityBaseFactory` object to either `main()` or the `ClientC` object, but not both which is the case in Appendix E.

A more difficult memory management problem to catch and fix occurs in the `ClientB` and `ClientC` objects regarding a shared `UtilityBase` object. When `shareUtility` is set to `false` (by the user in the commandline arguments) the objects `b1`, `b2` and `c` each own a pointer to different `UtilityBase` objects and the software will correctly delete each dynamically allocated object using one and only one call to `operator delete` (in the destructors of these classes). However, when `shareUtility` is set to `true` the objects `b1`, `b2` and `c` will contain pointers to the same `UtilityBase` object and `operator delete` will be called on this shared `UtilityBase` object multiple times when `b1`, `b2` and `c` are destroyed. In this case, it is not so easy to arbitrate ownership of the shared `UtilityBase` object to the `ClientB` or the `ClientC` objects. Logic could be developed in this simple program to insure that ownership was assigned properly but such logic would enlarge the program, complicate maintenance, and would ultimately make the software components less reusable. In more complex programs, trying to dynamically arbitrate ownership at run time is much more difficult and error prone if done manually.

2.2 Refactored example C++ program using `Teuchos::RCP`

Now we describe how `RCP` can be used to greatly simplify dynamic memory management in these types of OO programs. Appendix F shows the refactoring of the program in Appendix E to use `RCP` for all persisting relationships. In general, refactoring software that uses raw C++ pointers to use `RCP` is as simple as replacing the type `T*` with `RCP<T>`, where `T` is nearly any class or built-in data type.

The first persisting relationship for which `RCP` is used is the relationship between a `UtilityBaseFactory` object and a client that uses it. The refactoring changes the return type of `UtilityBaseFactory::createUtility()` from a raw `UtilityBase*` pointer to a `RCP<UtilityBase>` object. The new “Abstract Factory” class declarations (assuming that the symbols from the `Teuchos` namespace are in scope so that explicit `Teuchos::` qualification is not necessary) become

```
class UtilityBaseFactory {
public:
    virtual RCP<UtilityBase> createUtility() const = 0;
};

class UtilityAFactory : public UtilityBaseFactory {
public:
    RCP<UtilityBase> createUtility() const { return rcp(new UtilityA()); }
```

```
};

class UtilityBFactory : public UtilityBaseFactory {
public:
    RCP<UtilityBase> createUtility() const { return rcp(new UtilityB()); }
};
```

In addition to the change of the return type, the refactoring also requires that calls to operator new be wrapped in calls to the templated function `Teuchos::rcp(...)`.

The refactoring shown in Appendix F does not impact the definition of the class `ClientA` since this class does not have any persisting relationships with any other objects. However, the definitions of the classes `ClientB` and `ClientC` do change and become

```
class ClientB {
    RCP<UtilityBase> utility_;
public:
    void initialize(const RCP<UtilityBase> &utility) { utility_=utility; }
    void g( const ClientA &a ) { a.f(*utility_); }
};

class ClientC {
    RCP<UtilityBaseFactory> utilityFactory_;
    RCP<UtilityBase> utility_;
    bool shareUtility_;
public:
    ClientC( const RCP<UtilityBaseFactory> &utilityFactory, bool shareUtility )
        :utilityFactory_(utilityFactory),
        utility_(utilityFactory->createUtility())
        ,shareUtility_(shareUtility) {}
    void h( const Ptr<ClientB> &b ) {
        if( shareUtility_ ) b->initialize(utility_);
        else b->initialize(utilityFactory_->createUtility());
    }
};
```

The first thing that one should notice about the refactored `ClientB` and `ClientC` classes is that their destructors are gone. It turns out that the compiler-generated destructors do exactly the correct thing (i.e. call the destructor on the RCP data members which in turns calls operator delete on the underlying reference-counted object when the reference count goes to zero). The second thing that one should notice is that the old default constructor `ClientB::ClientB()` which initialized the raw C++ pointer `utility_` to null is no longer needed since RCP has a default constructor that does that. A third thing to notice about these refactored client classes is that the RCP objects are passed by const reference (see Appendix D) and not by value as the corresponding raw pointers where in the

original unrefactored classes. Passing RCP objects by const reference yields slightly more efficient code and simplifies stepping through the code in a debugger. For example, a function declared as

```
void someFunction( RCP<A> a );
```

will always result in the copy constructor for RCP being called (and therefore stepped into in a debugger) while this same function declared as:

```
void someFunction( const RCP<A> &a );
```

will often not require the copy constructor be called (except in cases where an implicit conversion is being performed as described in Appendix B) and thereby easing debugging.

Lastly, above, the class `Ptr` is a Teuchos non-reference-counted smart pointer class designed to avoid raw pointers. It is used for non-persisting associations where a raw pointer would otherwise be used. `Ptr` initializes to NULL and in debug mode it will throw exception exceptions when dereferencing NULL. `Ptr` plays a small role in the overall strategy to avoid all raw C++ pointers at the application programming level.

As an aside, note that Appendix D gives recommended idioms for how to pass raw C++ objects and RCP-wrapped objects to and from functions in a way that result in function prototypes becoming as self documenting as possible, help to avoid coding errors and increase the readability of C++ code. Also, in addition to the benefit that RCP eases dynamic memory management, the selective use of RCP and raw C++ object references extends the vocabulary of the C++ language by helping to distinguish between persisting and non-persisting associations. For example, when a one sees a function prototype where an object is passed through a RCP such as

```
class SomeClass {
public:
    void someFunction( const RCP<A> &a );
}
```

one can automatically deduce that “memory” of the A object will be retained (through a private RCP<A> data member in SomeClass no doubt) and that should automatically alter how the developer plans on calling that function and passing the A object. The refactored C++ program in Appendix F provides an example of how the idioms presented in Appendix D are put to use.

3 Additional and advanced features of RCP

The use cases for RCP described above comprise a large majority of the relevant use cases in most programs, but there there are some other use cases that require additional and more advanced fea-

tures. Some of these additional features (the C++ declarations for which are shown in Appendix A) are mentioned below:

1. Casting

RCP objects can be casted in a manner similar to casting raw C++ pointers and the same types of conversion rules apply. Analogs of the built-in casts `static_cast<>`, `const_cast<>` and `dynamic_cast<>` are supported by the non-member templated functions `rcp_static_cast<>`, `rcp_const_cast<>` and `rcp_dynamic_cast<>` respectively. See Appendix B for examples of how they are used.

2. Reference-count information

The function `RCP::count()` returns the number of RCP objects that point to the underlying reference-counted object. This information can be useful in some cases.

3. Customized deallocation policies

The default behavior of RCP is to call `operator delete` on reference-counted objects once the reference count goes to zero. While this is the most commonly needed behavior, there are use cases where more specialized deallocation policies are required. For these cases, there is an overloaded form of the templated function `Teuchos::rcp(...)` that takes a templated deallocation policy object that defines how a reference-counted object is deallocated when required.

4. Associating extra data with a reference-counted object

There are some more difficult use cases where certain types of information or other objects must be bundled with a reference-counted object and must not be deleted until the reference-counted object is deleted. The non-member templated functions `set_extra_data<>(...)` and `get_extra_data<>(...)` serve this purpose (see item (6) in Appendix B). Note that the extra data mechanism relies on an `std::map` and string comparisons etc. and can impart some unacceptably high overhead in some use cases.

5. Embedding an object on creation of an RCP object

Similar to the use of extra data, the RCP class also supports the concept of an embedded object. The functions `rcpWithEmbeddedObj[PreDestroy,PostDestroy](...)` (see 7 in Appendix B) can be used to create an RCP object and embed any other value-type object in the created `RCPNode`. This uses a customized deallocator class and imparts less overhead than the extra data feature at the cost of being less flexible (i.e. you can only embed a single value object and it must be done right when the first RCP object is created). The advantage of this approach is that access of the embedded object using the `get[Nonconst]-EmbeddedObj(...)` is faster than when using extra data but requires that you provide more information.

6. Checking for memory leaks from circular references

In a debug build, the user can enable checking for memory leaks caused by circular references among RCP objects. If circular references do exist, then RCPNode objects that were created but not removed are displayed at the end of a program. See the file `Teuchos_RCP.cpp` for details.

4 Summary

The templated C++ class RCP provides a low-overhead option for (almost) automatic memory management in C++. This class has been developed and refined over many years and has been instrumental in improving the quality of software projects that use it consistently (for example see MOOCHO [1]). Careful use of RCP eliminates the need to manually call `operator delete` when dynamically allocated objects are no longer needed. Furthermore, it helps to reduce the amount of code that developers have to write. For example, most classes that use RCP for dynamically allocated memory do not need developer-supplied destructors. This is because the compiler-generated destructors do the exactly correct thing which is to call destructors on an object's constituent data members. This was demonstrated in the difference between the original and refactored classes `ClientB` and `ClientC` described in Sections 2.1 and 2.2.

The class RCP also has advanced features not found in other smart-pointer implementations such as the ability to attach extra data and the customization of the deallocation policy.

References

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- [6] B. Stroustrup. *The C++ Programming Language, special edition*. Addison-Wesley, New York, 2000.

A C++ declarations for RCP

```
namespace Teuchos {

enum ENull { null };

enum EPrePostDestruction { PRE_DESTROY, POST_DESTROY };

template<class T>
class DeallocDelete { public: void free( T* ptr ) { if(ptr) delete ptr; } };

template<class T>
class DeallocArrayDelete { public: void free( T* ptr ) { if(ptr) delete [] ptr; } };

template<class T>
class RCP {
public:
    typedef T element_type;
    explicit RCP( T* ptr, bool owns_mem = true );
    RCP( ENull null_arg = null );
    RCP(const RCP<T>& r_ptr);
    template<class T2> RCP(const RCP<T2>& r_ptr);
    ~RCP();
    RCP<T>& operator=(const RCP<T>& r_ptr);
    T* operator->() const;
    T& operator*() const;
    T* get() const;
    T* release();
    int count() const;
    void set_has_ownership();
    bool has_ownership() const;
    bool shares_resource(const RCP<T>& r_ptr) const;
private:
    ...
};

template<class T>          RCP<T>   rcp( T* p );
template<class T>          RCP<T>   rcp( T* p, bool owns_mem);
template<class T,
    class Dealloc_T>      RCP<T>   rcp( T* p, Dealloc_T dealloc, bool owns_mem );
template<class T,
    class Embedded>       RCP<T>   rcpWithEmbeddedObjPreDestroy( T* p,
    const Embedded &embedded, bool owns_mem = true );
template<class T,
    class Embedded>       RCP<T>   rcpWithEmbeddedObjPostDestroy( T* p,
    const Embedded &embedded, bool owns_mem = true );
template<class T,
    class Embedded>       RCP<T>   rcpWithEmbeddedObj( T* p,
    const Embedded &embedded, bool owns_mem = true );
template<class T>          bool      is_null(const RCP<T>& p);
template<class T>          bool      operator==(const RCP<T>& p, ENull);
template<class T>          bool      operator!=(const RCP<T>& p, ENull);
template<class T2, class T1> bool      operator==(const RCP<T1>& p1,
    const RCP<T2>& p2 );
template<class T2, class T1> bool      operator!=(const RCP<T1>& p1,
    const RCP<T2>& p2 );
```

```

template<class T2, class T1> RCP<T2>      rcp_implicit_cast(const RCP<T1>& p1);
template<class T2, class T1> RCP<T2>      rcp_static_cast(const RCP<T1>& p1);
template<class T2, class T1> RCP<T2>      rcp_const_cast(const RCP<T1>& p1);
template<class T2, class T1> RCP<T2>      rcp_dynamic_cast(const RCP<T1>& p1,
                                bool throw_on_fail = false );
template<class T1, class T2> int           set_extra_data( const T1 &extra_data,
                                const std::string& name, const Ptr<RCP<T2> > &p,
                                bool force_unique = true,
                                EPrePostDestruction destroy_when = POST_DESTROY );
template<class T1, class T2> const T1&     get_extra_data( const RCP<T2>& p,
                                const std::string& name );
template<class T1, class T2> T1&          get_nonconst_extra_data( const RCP<T2>& p,
                                const std::string& name );
template<class T1, class T2> T1*          get_optional_extra_data( const RCP<T2>& p,
                                const std::string& name );
template<class T1, class T2> const T1*     get_optional_extra_data( const RCP<T2>& p,
                                const std::string& name );

template<class Dealloc_T,
class T> const Dealloc_T& get_dealloc( const RCP<T>& p );
template<class Dealloc_T,
class T> Dealloc_T&      get_nonconst_dealloc( const RCP<T>& p );
template<class Dealloc_T,
class T> const Dealloc_T* get_optional_dealloc( const RCP<T>& p );
template<class Dealloc_T,
class T> Dealloc_T*      get_optional_nonconst_dealloc( const RCP<T>& p );
template<class TOrig,
class Embedded, class T> const Embedded& getEmbeddedObj( const RCP<T>& p );
template<class TOrig,
class Embedded, class T> Embedded&      getNonconstEmbeddedObj( const RCP<T>& p );

} // namespace Teuchos

```

B RCP quick-start and reference

This appendix presents a short, but fairly comprehensive, quick-start for the use of RCP. The use cases described here should cover the overwhelming majority of the use instances of RCP in a typical program.

The following class hierarchy will be used in the C++ examples given below.

```
class A { public: virtual ~A(){} A& operator=(const A&){} virtual void f(){} };
class B1 : virtual public A {} ;
class B2 : virtual public A {} ;
class C : virtual public B1, virtual public B2 {} ;

class D {} ;
class E : public D {} ;
```

All of the following code examples used in this appendix are assumed to be in the namespace `Teuchos` or have appropriate using `Teuchos::...` declarations. This removes the need to explicitly use `Teuchos::` to qualify classes, functions and other declarations from the `Teuchos` namespace. Note that some of the runtime checks are denoted as “debug runtime checked” which means that checking will only be performed in a debug build (that is one where the macro `_DEBUG` is defined at compile time).

1. Creation of RCP objects

(a) Initializing a RCP object to NULL

```
RCP<C> c_ptr;

or

RCP<C> c_ptr = null;
```

(b) Creating a RCP object using `new`

```
RCP<C> c_ptr = rcp(new C);

or

RCP<C> c_ptr(new C);
```

(c) Creating a RCP object to an array allocated using `new[n]`

See the class `Teuchos::ArrayRCP`.

(d) Initializing a RCP object to an object not allocated with `new`

```
C      c;
RCP<C> c_ptr = rcp(&c,false);
```

(e) **Copy constructor (implicit casting)**

```
RCP<C>      c_ptr = rcp(new C); // No cast
RCP<A>      a_ptr = c_ptr;     // Cast to base class
RCP<const A> ca_ptr = a_ptr;   // Cast from non-const to const
```

(f) **Representing constantness and non-constantness**

i. **Non-constant pointer to non-constant object**

```
RCP<C> c_ptr;
```

ii. **Constant pointer to non-constant object**

```
const RCP<C> c_ptr;
```

iii. **Non-Constant pointer to constant object**

```
RCP<const C> c_ptr;
```

iv. **Constant pointer to constant object**

```
const RCP<const C> c_ptr;
```

2. **Reinitialization of RCP objects (using assignment operator)**

(a) **Resetting from a raw pointer**

```
RCP<A> a_ptr;
a_ptr = rcp(new A());
```

(b) **Resetting to null**

```
RCP<A> a_ptr = rcp(new A());
a_ptr = null; // The A object will be deleted here
```

(c) **Assigning from a RCP object**

```
RCP<A> a_ptr1;
RCP<A> a_ptr2 = rcp(new A());
a_ptr1 = a_ptr2; // Now a_ptr1 and a_ptr2 point to same A object
```

3. **Accessing the reference-counted object**

(a) **Access to object reference (debug runtime checked)**

```
C &c_ref = *c_ptr;
```

(b) **Access to object pointer (unchecked, may return NULL, NOT RECOMMENDED)**

```
C *c_rptr = c_ptr.get();
```

(c) **Access to object pointer (debug runtime checked, will not return NULL, NOT RECOMMENDED)**

```
C *c_rptr = &*c_ptr;
```

(d) **Access of object's member (debug runtime checked)**

```
c_ptr->f();
```

(e) **Testing for non-null**

```
if( !is_null(a_ptr) ) std::cout << "a_ptr is not null!\n";
```

or

```
if( a_ptr != null ) std::cout << "a_ptr is not null!\n";
```

(f) Testing for null

```
if( is_null(a_ptr) ) std::cout << "a_ptr is null!\n";
```

or

```
if( a_ptr == null ) std::cout << "a_ptr is null!\n";
```

4. Casting

(a) Implicit casting (see copy constructor above)

i. Using copy constructor (see above)

ii. Using conversion function

```
RCP<C>      c_ptr = rcp(new C);           // No cast  
RCP<A>      a_ptr = rcp_implicit_cast<A>(c_ptr); // To base  
RCP<const A> ca_ptr = rcp_implicit_cast<const A>(a_ptr); // To const
```

(b) Casting away const

```
RCP<const A> ca_ptr = rcp(new C);  
RCP<A>      a_ptr = rcp_const_cast<A>(ca_ptr); // cast away const!
```

(c) Static cast (no runtime check)

```
RCP<D> d_ptr = rcp(new E);  
RCP<E> e_ptr = rcp_static_cast<E>(d_ptr); // Unchecked, unsafe?
```

(d) Dynamic cast (runtime checked, failed cast allowed)

```
RCP<A> a_ptr = rcp(new C);  
RCP<B1> b1_ptr = rcp_dynamic_cast<B1>(a_ptr); // Checked, safe!  
RCP<B2> b2_ptr = rcp_dynamic_cast<B2>(b1_ptr); // Checked, safe!  
RCP<C> c_ptr = rcp_dynamic_cast<C>(b2_ptr); // Checked, safe!
```

(e) Dynamic cast (runtime checked, failed cast not allowed)

```
RCP<A> a_ptr1 = rcp(new C);  
RCP<A> a_ptr2 = rcp(new A);  
RCP<B1> b1_ptr1 = rcp_dynamic_cast<B1>(a_ptr1,true); // Success!  
RCP<B1> b1_ptr2 = rcp_dynamic_cast<B1>(a_ptr2,true); // Throw std::bad_cast!
```

5. Customized deallocators

(a) Creating a RCP object with a custom deallocator

```
RCP<C> c_ptr = rcp(new C[N], DeallocArrayDelete<C>(), true);
```

(b) Access customized deallocator (runtime checked, throws on failure)

```
const DeallocArrayDelete<C>  
&dealloc = get_dealloc<DeallocArrayDelete<C> >(c_ptr);
```

(c) Access optional customized deallocator

```
const DeallocArrayDelete<C>  
*dealloc = get_optional_dealloc<DeallocArrayDelete<C> >(c_ptr);  
if(dealloc) std::cout << "This deallocator exits!\n";
```

6. Managing extra data

(a) Adding extra data (post destruction of extra data)

```
set_extra_data(rcp(new B1), "A:B1", &a_ptr);
```

(b) Adding extra data (pre destruction of extra data)

```
set_extra_data(rcp(new B1), "A:B1", &a_ptr, PRE_DESTROY);
```

(c) Retrieving extra data

```
get_extra_data<RCP<B1> >(a_ptr, "A:B1")->f();
```

(d) Resetting extra data

```
get_extra_data<RCP<B1> >(a_ptr, "A:B1") = rcp(new C);
```

(e) Retrieving optional extra data

```
const RCP<B1> *b1 = get_optional_extra_data<RCP<B1> >(a_ptr, "A:B1");  
if(b1) (*b1)->f();
```

7. Embedded objects

(a) Creating an RCP object with embedded data

```
RCP<D> d_ptr(new D);  
RCP<A> a_ptr rcpWithEmbeddedObj(new C, rcp(new D));
```

(b) Extract reference to const embedded object

```
const RCP<D> &d_ptr = getEmbeddedObj<C, RCP<D> >(a_ptr);
```

(c) Extract reference to nonconst embedded object

```
RCP<D> &d_ptr = getNonconstEmbeddedObj<C, RCP<D> >(a_ptr);  
d_ptr = null; // Sets the actual embedded RCP<D> object in a_ptr to null!
```

C Commandments for the use of RCP

Here are listed commandments for the use of RCP. These commandments reinforce some of the material in the quick-start in Appendix B. Along with each commandment is one or more anti-commandments stating the negative of the commandment. C++ code fragments are also included to demonstrate each commandment and anti-commandment.

Commandment 1 *Thou shall put a pointer for an object allocated with operator new into a RCP object only once. The best way to insure this is to call operator new directly in a call to rcp(. . .) to create a dynamically allocated object that is to be managed by a RCP object. See item (1b) in Appendix B.*

Anti-Commandment 1 *Thou shall never give a raw C++ pointer returned from operator new to more than one RCP object.*

Example:

```
A *ra_ptr = new C;
RCP<A> a_ptr1 = rcp(ra_ptr); // Okay
RCP<A> a_ptr2 = rcp(ra_ptr); // no, No, NO !!!!
```

Anti-Commandment 2 *Thou shall never give a raw C++ pointer to an array of objects returned from operator new[] to a RCP object using rcp(new C[n]).*

Example:

```
RCP<std::vector<C> > c_array_ptr1 = rcp(new std::vector<C>(N)); // Okay
RCP<C> c_array_ptr3 = rcp(new C[n]); // no, No, NO!
```

Commandment 2 *Thou shall only create a NULL RCP object by using the default constructor or by using the null enum (and its associated special constructor) (see item (1a) in Appendix B). Trying to assign to NULL or 0 will not compile.*

Anti-Commandment 3 *Thou shall not create a NULL RCP object using the templated function rcp(. . .) since it is very verbose and complicates maintenance.*

Example:

```
RCP<A> a_ptr1 = null;           // Yes :-)
RCP<A> a_ptr2 = rcp<A>(NULL); // No, too verbose :-)
```

Commandment 3 *Thou shall only pass a raw pointer for an object that is not allocated by operator new (e.g. allocated on the stack) into a RCP object by using the templated function `rcp<T>(T* p, bool owns_mem)` and setting `owns_mem` to `false` (see item (1d) in Appendix B).*

Anti-Commandment 4 *Thou shall never pass a pointer for an object not allocated with operator new into a RCP object without setting `owns_mem` to `false`.*

Example:

```
C c;
RCP<A> a_ptr1 = rcp(&c,false); // Yes :-)
RCP<A> a_ptr2 = rcp(&c);      // no, No, NO !!!!
```

Commandment 4 *Thou shall only cast between RCP objects using the default copy constructor (for implicit conversions) and the nonmember template functions `rcp_implicit_cast<>(...)`, `rcp_static_cast<>(...)`, `rcp_const_cast<>(...)` and `rcp_dynamic_cast<>(...)` (see item (4) in Appendix B).*

Anti-Commandment 5 *Thou shall never convert between RCP objects using raw pointer access.*

Example:

```
RCP<A>    a_ptr  = rcp(new C);
RCP<B1>  b1_ptr1 = rcp_dynamic_cast<B1>(a_ptr); // Yes :-)
RCP<B1>  b1_ptr2 = rcp(dynamic_cast<B1*>(a_ptr.get())); // no, No, NO !!!!
```

D Recommendations for passing objects to and from C++ functions

Below are recommended idioms for passing required¹ and optional² arguments into and out of C++ functions for various use cases and different types of objects. These idioms show how to write function prototype argument declarations which exploit the C++ language in a way that makes these function prototypes as self documenting as possible, avoids coding errors, and increases readability³ of C++ code. In general, `RCP<T>` objects should be passed and manipulated as though they were raw C++ pointer `T*` objects. However, while raw C++ pointer objects should generally be passed by value, `RCP` objects should generally be passed by reference for several reasons.

Argument purpose	Non-Persisting	Persisting
non-changeable object (required ¹)	<code>S s</code> or <code>const S s</code> or <code>const S &s</code>	<code>const RCP<const S> &s</code>
non-changeable object (optional ²)	<code>const Ptr<const S> &s</code>	<code>const RCP<const S> &s</code>
changeable object	<code>const Ptr<S> &s</code>	<code>const RCP<S> &s</code>

C++ declarations for passing small concrete objects (i.e. with value semantics) to and from functions where `S` is a place holder for an actual built-in or user-defined data type.

Argument purpose	Non-Persisting	Persisting
non-changeable object (required ¹)	<code>const A &a</code>	<code>const RCP<const A> &a</code>
non-changeable object (optional ²)	<code>const Ptr<const A> &a</code>	<code>const RCP<const A> &a</code>
changeable object	<code>const Ptr<A> &a</code>	<code>const RCP<A> &a</code>

C++ declarations for passing abstract objects (i.e. with reference or pointer semantics) or large concrete objects (i.e. that are too expensive to copy) to and from functions where `A` is a place holder for an actual abstract C++ base class.

¹Required arguments must be bound to valid objects (i.e. can not be `NULL`)

²Optional arguments may be `NULL` in some cases

³What makes code more “readable” is subjective of course.

E Listing: Example C++ program using raw dynamic memory management

```
#include "example_get_args.hpp"

// Abstract interfaces
class UtilityBase {
public:
    virtual void f() const = 0;
};
class UtilityBaseFactory {
public:
    virtual UtilityBase* createUtility() const = 0;
};

// Concrete implementations
class UtilityA : public UtilityBase {
public:
    void f() const { std::cout<<"\nUtilityA::f() called, this="<<this<<"\n"; }
};
class UtilityB : public UtilityBase {
public:
    void f() const { std::cout<<"\nUtilityB::f() called, this="<<this<<"\n"; }
};
class UtilityAFactory : public UtilityBaseFactory {
public:
    UtilityBase* createUtility() const { return new UtilityA(); }
};
class UtilityBFactory : public UtilityBaseFactory {
public:
    UtilityBase* createUtility() const { return new UtilityB(); }
};

// Client classes
class ClientA {
public:
    void f( const UtilityBase &utility ) const { utility.f(); }
};
class ClientB {
    UtilityBase *utility_;
public:
    ClientB() : utility_(0) {}
    ~ClientB() { delete utility_; }
    void initialize( UtilityBase *utility ) { utility_ = utility; }
    void g( const ClientA &a ) { a.f(*utility_); }
};
class ClientC {
```

```

const UtilityBaseFactory *utilityFactory_;
UtilityBase *utility_;
bool shareUtility_;
public:
ClientC( const UtilityBaseFactory *utilityFactory, bool shareUtility )
    :utilityFactory_(utilityFactory)
    ,utility_(utilityFactory->createUtility())
    ,shareUtility_(shareUtility) {}
~ClientC() { delete utilityFactory_; delete utility_; }
void h( ClientB *b ) {
    if( shareUtility_ ) b->initialize(utility_);
    else b->initialize(utilityFactory_->createUtility());
}
};

// Main program
int main( int argc, char* argv[] )
{
    // Read options from the commandline
    bool useA, shareUtility;
    example_get_args(argc,argv,&useA,&shareUtility);
    // Create factory
    UtilityBaseFactory *utilityFactory = 0;
    if(useA) utilityFactory = new UtilityAFactory();
    else    utilityFactory = new UtilityBFactory();
    // Create clients
    ClientA a;
    ClientB b1, b2;
    ClientC c(utilityFactory,shareUtility);
    // Do some stuff
    c.h(&b1);
    c.h(&b2);
    b1.g(a);
    b2.g(a);
    // Cleanup memory
    delete utilityFactory;
}

```

F Listing: Refactored example C++ program using RCP

```
#include "Teuchos_RCP.hpp"
#include "example_get_args.hpp"

// Inject symbols for RCP so we don't need Teuchos:: qualification
using Teuchos::RCP;
using Teuchos::rcp; // Warning! This can be dangerous and is not to be used in general!
using Teuchos::Ptr;

// Abstract interfaces
class UtilityBase {
public:
    virtual void f() const = 0;
};
class UtilityBaseFactory {
public:
    virtual RCP<UtilityBase> createUtility() const = 0;
};

// Concrete implementations
class UtilityA : public UtilityBase {
public:
    void f() const { std::cout<<"\nUtilityA::f() called, this="<<this<<"\n"; }
};
class UtilityB : public UtilityBase {
public:
    void f() const { std::cout<<"\nUtilityB::f() called, this="<<this<<"\n"; }
};
class UtilityAFactory : public UtilityBaseFactory {
public:
    RCP<UtilityBase> createUtility() const { return rcp(new UtilityA()); }
};
class UtilityBFactory : public UtilityBaseFactory {
public:
    RCP<UtilityBase> createUtility() const { return rcp(new UtilityB()); }
};

// Client classes
class ClientA {
public:
    void f( const UtilityBase &utility ) const { utility.f(); }
};
class ClientB {
    RCP<UtilityBase> utility_;
public:
    void initialize(const RCP<UtilityBase> &utility) { utility_=utility; }
```

```

    void g( const ClientA &a ) { a.f(*utility_); }
};
class ClientC {
    RCP<const UtilityBaseFactory> utilityFactory_;
    RCP<UtilityBase> utility_;
    bool shareUtility_;
public:
    ClientC( const RCP<const UtilityBaseFactory> &utilityFactory, bool shareUtility )
        :utilityFactory_(utilityFactory)
        ,utility_(utilityFactory->createUtility())
        ,shareUtility_(shareUtility) {}
    void h( const Ptr<ClientB> &b ) {
        if( shareUtility_ ) b->initialize(utility_);
        else b->initialize(utilityFactory_->createUtility());
    }
};

// Main program
int main( int argc, char* argv[] )
{
    // Read options from the commandline
    bool useA, shareUtility;
    example_get_args(argc,argv,&useA,&shareUtility);
    // Create factory
    RCP<UtilityBaseFactory> utilityFactory;
    if(useA) utilityFactory = rcp(new UtilityAFactory());
    else    utilityFactory = rcp(new UtilityBFactory());
    // Create clients
    ClientA a;
    ClientB b1, b2;
    ClientC c(utilityFactory,shareUtility);
    // Do some stuff
    c.h(&b1);
    c.h(&b2);
    b1.g(a);
    b2.g(a);
}

```